

Quantum Mechanics I

**Kinematics
vs. Dynamics**

Transformations

Symmetries

Application

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Pink Floyd: "Another Brick in the Wall (Pt. II)"

Kinematics vs. Dynamics

Transformations

● Disclaimer: focus on pure states $\hat{\rho} = |\psi\rangle\langle\psi|$

● extend results to mixed states using that for all mixed states

$$\begin{aligned}\hat{\rho} &= \sum_n \rho_n |\rho_n\rangle\langle\rho_n| & \hat{\rho} |\rho_n\rangle &= \rho_n |\rho_n\rangle & 0 \leq \rho_n \leq 1, & \sum_n \rho_n = 1 \\ &= \sum_n \varrho_n |n\rangle\langle n| & \forall |n\rangle \in \mathcal{D}_{\hat{\rho}}, & \langle n'|n\rangle = \delta_{n',n}, & \sum_n |n\rangle\langle n| = \mathbb{1} \\ & & & & 0 \leq \varrho_n \leq 1, & \sum_n \varrho_n = 1\end{aligned}$$

● Among other things,

$$|\chi\rangle = A|\psi\rangle \quad \Rightarrow \quad |\chi\rangle\langle\chi| = A|\psi\rangle\langle\psi|A^\dagger$$

$$\hat{\rho}' = A\hat{\rho}A^\dagger \quad \text{in fact, all operators, in general for all states, pure and mixed}$$

● Also,

$$\begin{aligned}\langle R \rangle_{\hat{\rho}} &= \text{Tr}[\hat{\rho} R] = \text{Tr}\left[\sum_n \varrho_n |n\rangle\langle n| R\right] = \sum_n \varrho_n \text{Tr}[|n\rangle\langle n| R] \\ &= \sum_n \varrho_n \text{Tr}[\langle n| R |n\rangle] = \sum_n \varrho_n \langle n| R |n\rangle = \langle\psi| R |\psi\rangle \text{ if } \varrho_n = \delta_{n,\psi}\end{aligned}$$

Kinematics vs. Dynamics

Transformations

- Laws of nature—& observables—are coordinate-independent
- up to proper coordinate transformations (such as rotation, $F_x \rightarrow R \cdot F_x$)

○ Thus, $A |\phi_n\rangle = a_n |\phi_n\rangle \Rightarrow A' |\phi'_n\rangle = a_n |\phi'_n\rangle$

$$|\psi\rangle = \sum_n c_n |\phi_n\rangle \Rightarrow |\psi'\rangle = \sum_n c'_n |\phi'_n\rangle$$

$$|c_n|^2 = |c'_n|^2 \quad \text{i.e.,} \quad |\langle \phi_n | \psi \rangle|^2 = |\langle \phi'_n | \psi' \rangle|^2$$

- BTW: Classical probabilistic physics (stat. mech.) may be phrased in terms of **probabilities**. *conservation of probability*
- Quantum mechanics is phrased in terms of (complex!) **probability amplitudes**
- Probability = |probability amplitude|²
- the (overall) phase of the probability amplitude is not observable
- relative phases induce interference—QM hallmark

Kinematics vs. Dynamics

Symmetries

● Theorem [Wigner]:

● Any mapping of a vector space (of pure states) onto itself

● preserving amplitudes of probability may be implemented by a U

● which is either unitary (& linear) or antiunitary (and antilinear).

● Unitary (& linear): $UU^\dagger = U^\dagger U = \mathbf{1}$

$$\langle \phi' | \psi' \rangle = (\langle \phi | U^\dagger) (U | \psi \rangle) = \langle \phi | \underbrace{U^\dagger U}_{=\mathbf{1}} | \psi \rangle = \langle \phi | \psi \rangle$$

Unitary:
 $UAU^\dagger = UAU^{-1}$
(similarity tr.)

● Antiunitary (& antilinear): $A c | \psi \rangle = c^* A | \psi \rangle$

$$\langle \phi' | \psi' \rangle = \langle \phi A^\dagger | A \psi \rangle = \langle \phi | \psi \rangle^*$$

● $\mathbf{1}$ is unitary.

● Continuous transformations “tunable” to $\mathbf{1}$ must be unitary

● Discrete transformations can be either of the two.

Kinematics vs. Dynamics

Symmetries

- For all unitary transformations
- operators transform as $A \rightarrow A' = UAU^\dagger = UAU^{-1}$
- Physical transformations *concatenate*
- For a $U(s)$ such that $U(0)=1$ and $U(s_1)U(s_2)=U(s_1+s_2)$,
- In general, [Unitary operator] = $e^{i[\text{Hermitian operator}]}$
generator
- Non-relativistic space-time symmetries
 - (1) Time translation: $t \rightarrow t' = t + t_0$
 - (3) Space translation: $\mathbf{r} \rightarrow \mathbf{r}' = \mathbf{r} + \mathbf{r}_0$
 - (3) Space rotation: $\mathbf{r} \rightarrow \mathbf{r}' = R(\mathbf{r}) = \mathbf{n}(\mathbf{n} \cdot \mathbf{r}) + (\mathbf{n} \times \mathbf{r}) \sin\theta + [\mathbf{r} - \mathbf{n}(\mathbf{n} \cdot \mathbf{r})] \cos\theta$
 - (3) Constant-velocity boosts: $\mathbf{v} \rightarrow \mathbf{v}' = \mathbf{v} + \mathbf{v}_0$
 - These 10 transformations comprise the Galilean group
 - Notice: $\text{boost}(\mathbf{r}) = \mathbf{r} + \mathbf{v}_0 t$, but $\text{boost}(t) = t$

Kinematics vs. Dynamics

Symmetries

Generators:

- time-translation: H
- space-translation: P_α
- space-rotation: J_α
- velocity boost: G_α not very familiar...

In general: $e^{i\varepsilon A} e^{i\varepsilon B} e^{-i\varepsilon A} e^{-i\varepsilon B} = 1 + \varepsilon^2[A, B] + \dots$

Using only **geometry** and the **Jacobi identities*** (essentially, **meaning** and **consistency**)

(a) $[P_\alpha, P_\beta] = 0$	(f) $[G_\alpha, P_\beta] = i\delta_{\alpha\beta}\hbar M \mathbb{1}$
(b) $[G_\alpha, G_\beta] = 0$	(g) $[P_\alpha, H] = 0$
(c) $[J_\alpha, J_\beta] = i\varepsilon_{\alpha\beta\gamma}\hbar J_\gamma$	(h) $[J_\alpha, H] = 0$
(d) $[J_\alpha, P_\beta] = i\varepsilon_{\alpha\beta\gamma}\hbar P_\gamma$	(i) $[G_\alpha, H] = i\hbar P_\alpha \mathbb{1}$
(e) $[J_\alpha, G_\beta] = i\varepsilon_{\alpha\beta\gamma}\hbar G_\gamma$	

* $[A, [B, C]] + [B, [C, A]] + [C, [A, B]] = 0$

Kinematics vs. Dynamics

Identifications, i.e. Application

Galilean symmetries

Space-Time Transformation	Unitary Operator	Generator
Rotation about the α -axis $\mathbf{r} \rightarrow R_\alpha(\theta) \cdot \mathbf{r}$	$\exp \{ -i\theta J_\alpha / \hbar \}$	(angular momentum) J_α
Translation along the α -axis $x_\alpha \rightarrow x_\alpha + a$	$\exp \{ -ia P_\alpha / \hbar \}$	(linear momentum) P_α
Velocity boost along the α -axis $x_\alpha \rightarrow x_\alpha + v_0 t$	$\exp \{ iv_0 G_\alpha / \hbar \}$	(Galilean boost) G_α
Time-translation $t \rightarrow t + t_0$	$\exp \{ it_0 H / \hbar \}$	(Hamiltonian) H

Kinematics vs. Dynamics

Identifications, i.e. Application

- We need a way to assess position. Define Q_α as the Hermitian (Cartesian coordinate) position operator
- Then, $Q_\alpha |\mathbf{r}\rangle = x_\alpha |\mathbf{r}\rangle$ $[Q_\alpha, Q_\beta] = 0$ $-\infty \leq x_\alpha \leq +\infty$
- From the geometric meaning of P_α , and J_α , it follows that

$$Q'_\alpha = e^{-i\mathbf{a}\cdot\mathbf{P}/\hbar} Q_\alpha e^{+i\mathbf{a}\cdot\mathbf{P}/\hbar} \stackrel{!}{=} Q_\alpha - a_\alpha \mathbb{1}$$

space translations translate Q_α

$$[Q_\alpha, P_\beta] = i\hbar\delta_{\alpha\beta} \mathbb{1}$$

CCR

$$Q'_\alpha = e^{-i\boldsymbol{\theta}\cdot\mathbf{J}/\hbar} Q_\alpha e^{+i\boldsymbol{\theta}\cdot\mathbf{J}/\hbar} \stackrel{!}{=} Q_\alpha + \varepsilon_{\alpha\beta\gamma} \theta_\beta Q_\gamma \mathbb{1}$$

$$[J_\alpha, Q_\beta] = i\hbar\varepsilon_{\alpha\beta\gamma} Q_\gamma \mathbb{1}$$

space rotations... rotate Q_α

$$Q'_\alpha = e^{-i\mathbf{v}\cdot\mathbf{G}(t)/\hbar} Q_\alpha e^{+i\mathbf{v}\cdot\mathbf{G}(t)/\hbar} \stackrel{!}{=} Q_\alpha - v_\alpha t \mathbb{1}$$

$$\mathbf{G}_\alpha(t) = M Q_\alpha - t P_\alpha$$

velocity boosts... t -dependently translate Q_α ...for a free particle

Try exercise 3.7. Then check Ballentine's solution on p. 621–622

Kinematics vs. Dynamics

Identifications, i.e. Application

Finally, define V_α such that $\langle V_\alpha \rangle := \frac{d}{dt} \langle Q_\alpha \rangle = \frac{d}{dt} \langle \Psi | Q_\alpha | \Psi \rangle$

Calculate:

$$\frac{d}{dt} \langle \Psi | Q_\alpha | \Psi \rangle = \left(\frac{d}{dt} \langle \Psi | \right) Q_\alpha | \Psi \rangle + \langle \Psi | \left(\frac{d}{dt} Q_\alpha \right) | \Psi \rangle + \langle \Psi | Q_\alpha \left(\frac{d}{dt} | \Psi \rangle \right)$$

measuring position is time-independent

$$\frac{d}{dt} | \Psi \rangle := \lim_{\epsilon \rightarrow 0} \frac{| \Psi(t+\epsilon) \rangle - | \Psi(t) \rangle}{\epsilon} = \lim_{\epsilon \rightarrow 0} \frac{e^{-i\epsilon H/\hbar} | \Psi(t) \rangle - | \Psi(t) \rangle}{\epsilon}$$

$$= \lim_{\epsilon \rightarrow 0} \frac{[\mathbb{1} - i\epsilon H/\hbar + \dots] | \Psi(t) \rangle - | \Psi(t) \rangle}{\epsilon} = \frac{1}{i\hbar} H | \Psi(t) \rangle$$

$$\langle \Psi | V_\alpha | \Psi \rangle = \left(-\frac{1}{i\hbar} \langle \Psi(t) | H \right) Q_\alpha | \Psi(t) \rangle + \langle \Psi(t) | Q_\alpha \left(\frac{1}{i\hbar} H | \Psi(t) \rangle \right)$$

$$= \frac{i}{\hbar} \langle \Psi(t) | [H, Q_\alpha] | \Psi(t) \rangle$$

$$V_\alpha := \frac{i}{\hbar} [H, Q_\alpha]$$

general definition

Verify:

$$V'_\alpha = e^{i\mathbf{v} \cdot \mathbf{G}/\hbar} V_\alpha e^{-i\mathbf{v} \cdot \mathbf{G}/\hbar} = V_\alpha - \mathbf{v}_\alpha \mathbb{1}$$

Kinematics vs. Dynamics

Identifications, i.e. Application

- Verify that $L_\alpha := i\hbar \varepsilon_{\alpha\beta\gamma} Q_\beta P_\gamma$ satisfies $[L_\alpha, L_\beta] = i\hbar \varepsilon_{\alpha\beta\gamma} L_\gamma$
- So define $J_\alpha := L_\alpha + S_\alpha$, where $[L_\alpha, S_\beta] = 0$ and $[S_\alpha, S_\beta] = i\hbar \varepsilon_{\alpha\beta\gamma} S_\gamma$
- Now, define the (space) coordinate representation:

$$\Psi(\mathbf{r}, t) := \langle \mathbf{r} | \Psi(t) \rangle \quad R\Psi(\mathbf{r}, t) := \langle \mathbf{r} | R | \Psi(t) \rangle$$

state-function (over space)

- Then
$$e^{-i\theta \cdot J} \Psi(\mathbf{r}, t) = \langle \mathbf{r} | e^{-i\theta \cdot J} | \Psi(t) \rangle = \langle \mathbf{r} | e^{-i\theta \cdot (L + S)} | \Psi(t) \rangle$$

- Thus: L_α is “positional,” while S_α is “directional.”

- Historically: L_α is “orbital,” while S_α is “spin.”

- On the other hand, $i\hbar P_\alpha = [G_\alpha, H] = [MQ_\alpha - t P_\alpha, H]$

- fits $H = \frac{1}{2M} |\vec{P} + \vec{A}(\mathbf{Q})|^2 + W(\mathbf{Q})$
most general non-relativistic Hamiltonian

Potential \Rightarrow no t-dependent transl.

Quantum Mechanics I

*Now, go forth and
calculate!!!*



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